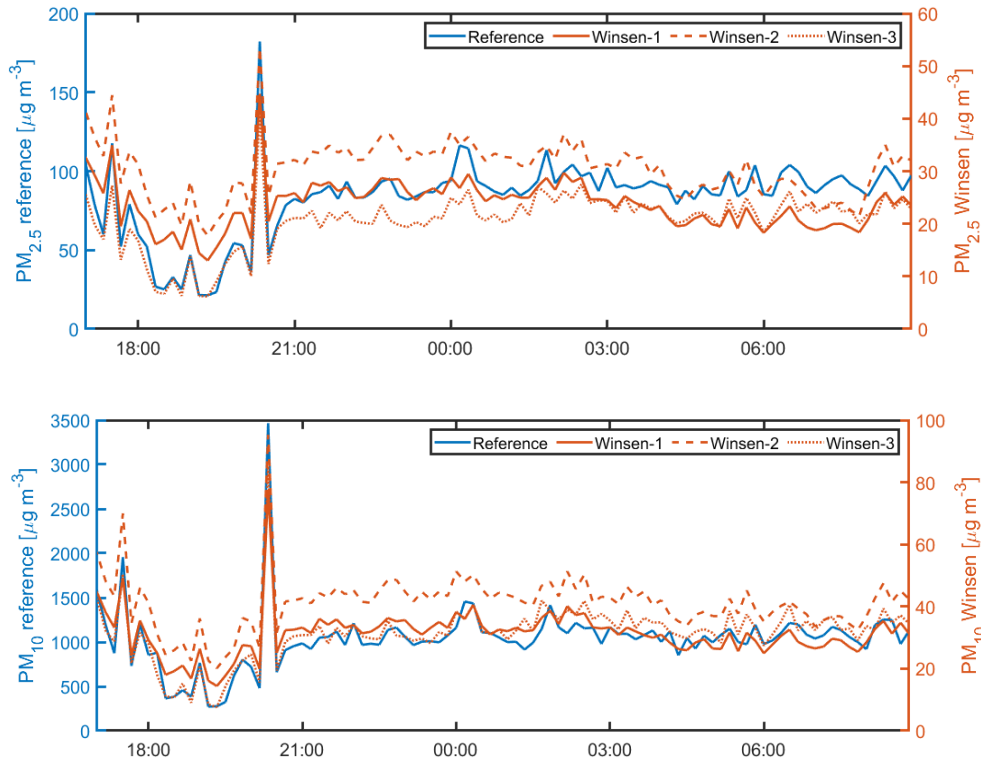
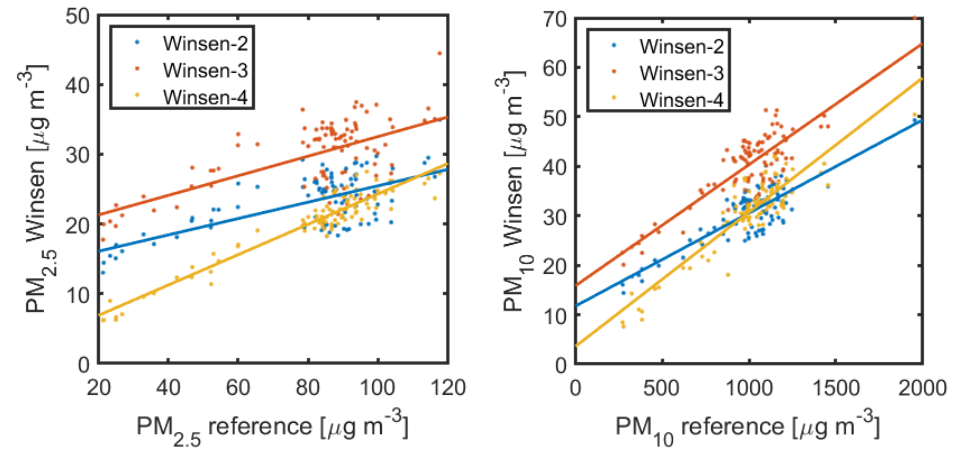




## Uncalibrated sensor vs reference



## Linearity before calibration



$R^2 \geq 0.40$

slopes are around

- 0.15 for  $PM_{2.5}$
- 0.02 for  $PM_{10}$

## Accuracy (uncalibrated)

Reference mean ( $\mu\text{g}/\text{m}^3$ )		Accuracy (%)	
$PM_{2.5}$	$PM_{10}$	$PM_{2.5}$	$PM_{10}$
19	206	25	3
32	401	24	3
84	846	22	3
126	1267	19	3
163	1649	20	3

**Data recovery**  
95% for all units

**Influence of T and RH**  
Changes in T and RH **do not affect** the sensor.



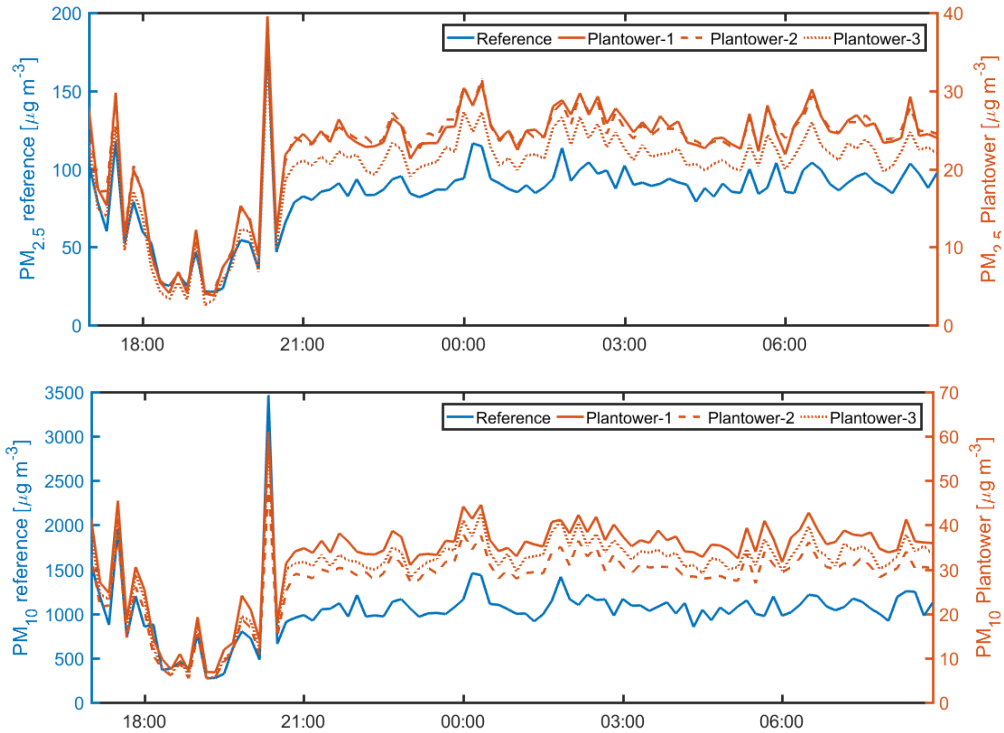
**None** of the three sensors worked properly during the PM lab testing.

Only **one** of the three sensors gave a signal, and the signal **did not** correlate with the reference measurements ( $R^2 < 0.01$ ).

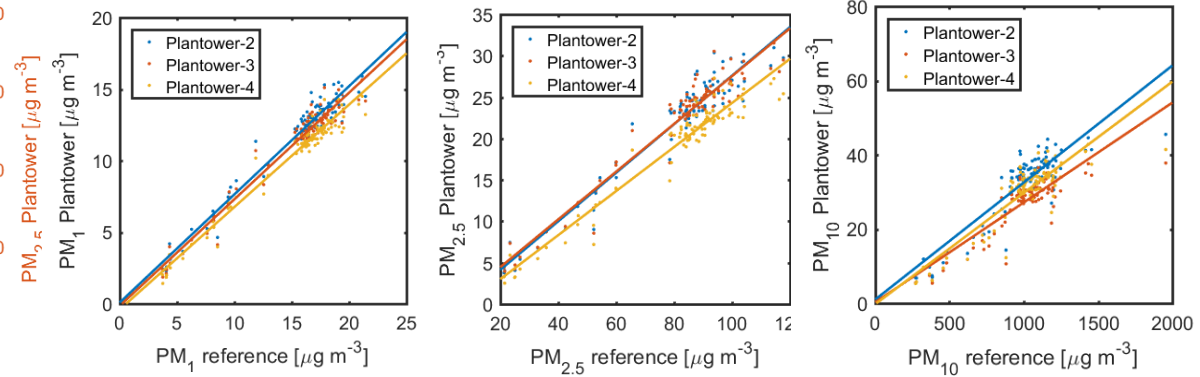
The units were returned to the manufacturer for servicing.



## Uncalibrated sensor vs reference



## Linearity before calibration



$R^2 \geq 0.76$   
 slopes are around

- 0.95 for  $PM_1$
- 0.93 for  $PM_{2.5}$
- 0.03 for  $PM_{10}$

## Accuracy (uncalibrated)

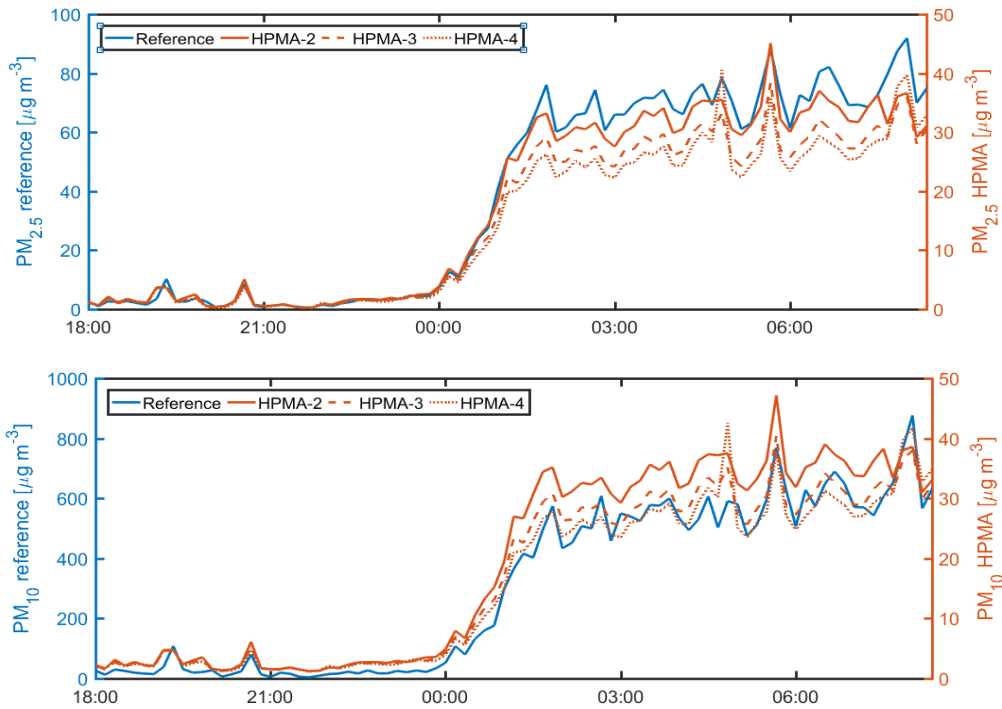
Reference mean ( $\mu\text{g}/\text{m}^3$ )			Accuracy (%)		
$PM_1$	$PM_{2.5}$	$PM_{10}$	$PM_1$	$PM_{2.5}$	$PM_{10}$
3	19	206	51	16	2
5	32	401	65	23	3
16	84	846	69	25	3
24	126	1267	68	25	3
30	163	1649	62	23	3

**Data recovery**  
**95% for all units**

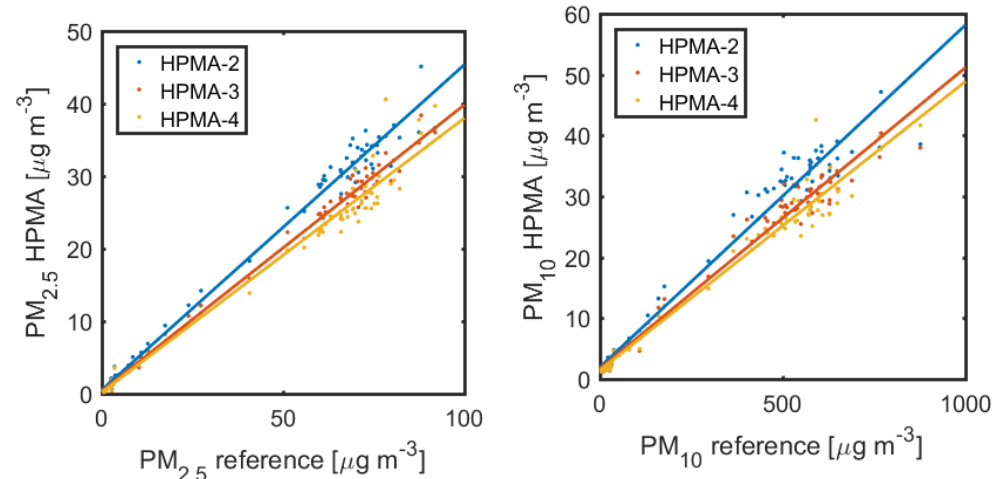
**Influence of T and RH**  
 Changes in RH somewhat **affect** the sensor.  
**One** unit sensitive to changes in T



## Uncalibrated sensor vs reference



## Linearity before calibration



$R^2 \geq 0.97$   
 slopes are around  
 ➤ 0.41 for  $PM_{2.5}$   
 ➤ 0.048 for  $PM_{10}$

## Accuracy (uncalibrated)

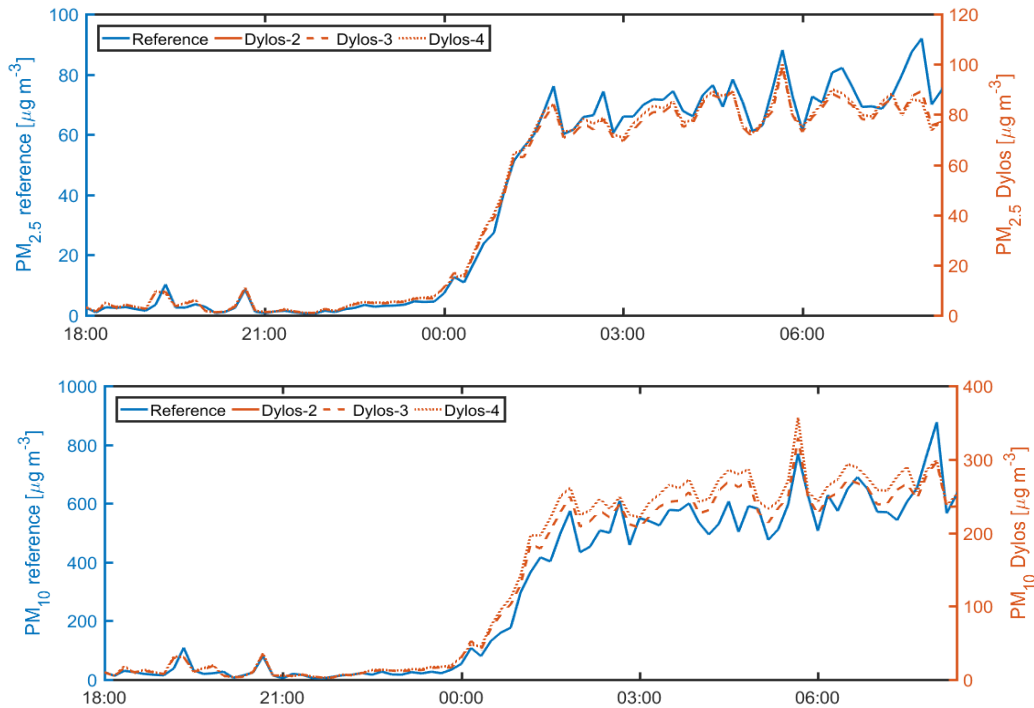
Reference mean ( $\mu\text{g}/\text{m}^3$ )		Accuracy (%)	
$PM_{2.5}$	$PM_{10}$	$PM_{2.5}$	$PM_{10}$
38	398	48	5
46	510	47	5
77	632	45	6
88	726	45	6
136	1016	42	5

**Data recovery**  
**100% for all units**

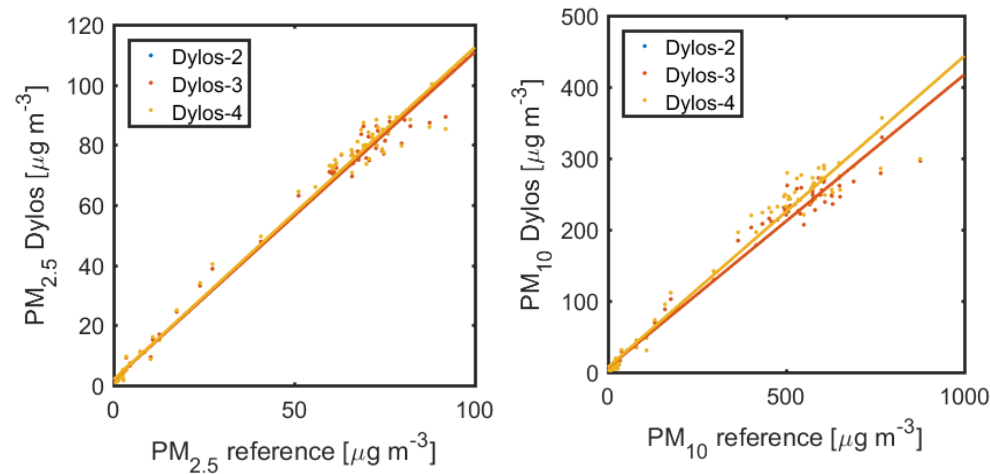
**Influence of T and RH**  
 Changes in RH **affect** the sensor



## Uncalibrated sensor vs reference



## Linearity before calibration



$R^2 \geq 0.97$   
 slopes are around  
 ➤ 1.1 for  $PM_{2.5}$   
 ➤ 0.42 for  $PM_{10}$

## Accuracy (uncalibrated)

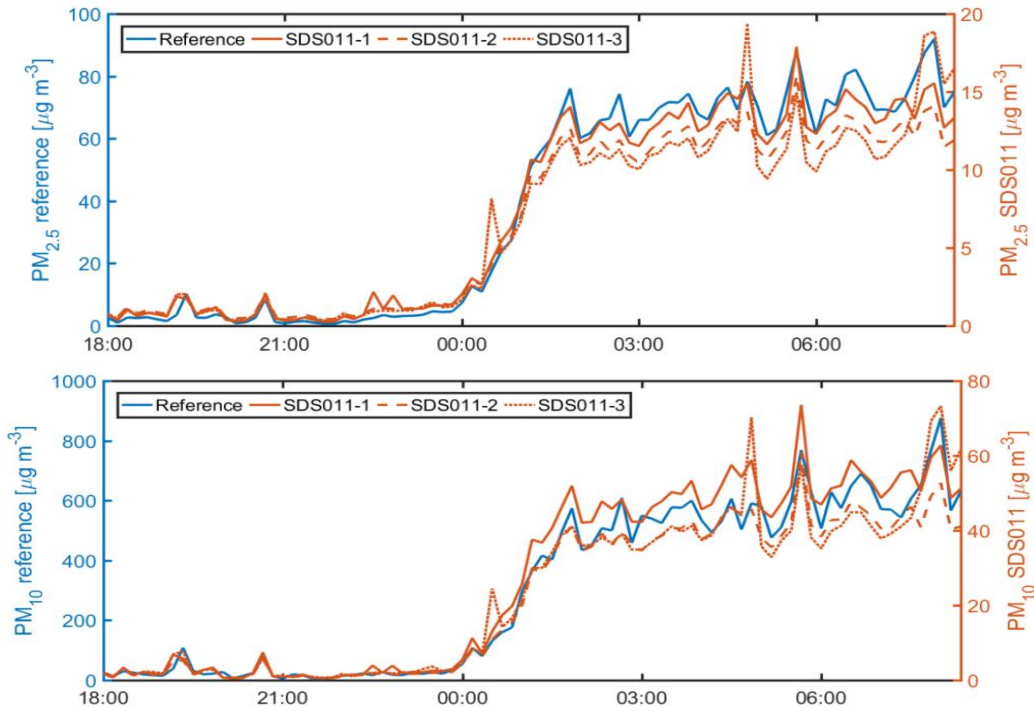
Reference mean ( $\mu\text{g}/\text{m}^3$ )		Accuracy (%)	
$PM_{2.5}$	$PM_{10}$	$PM_{2.5}$	$PM_{10}$
38	398	46	62
46	510	44	54
77	632	45	65
88	726	50	58
136	1016	52	58

**Data recovery**  
 99% for two units  
 One unit could not be tested due to power issues

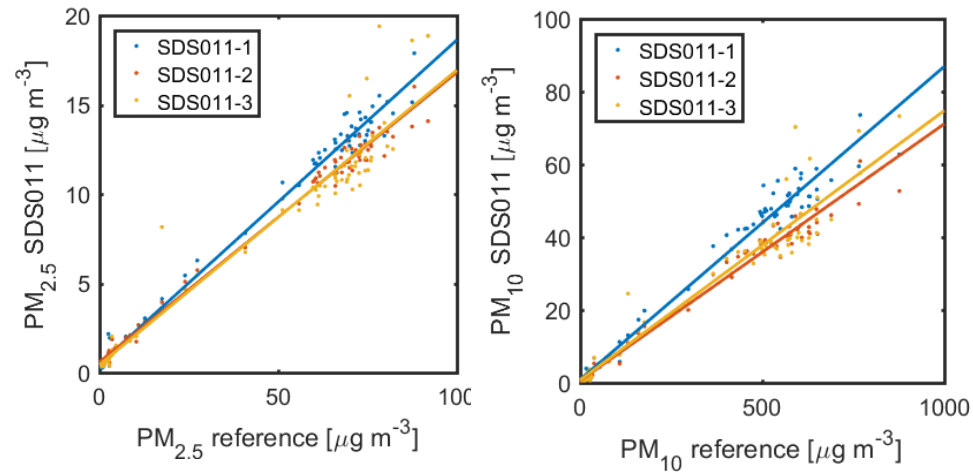
**Influence of T and RH**  
 Changes in T and RH somewhat affect the sensor



## Uncalibrated sensor vs reference



## Linearity before calibration



$R^2 \geq 0.94$   
 slopes are around  
 ➤ 0.17 for  $PM_{2.5}$   
 ➤ 0.079 for  $PM_{10}$

## Accuracy (uncalibrated)

Reference mean ( $\mu\text{g}/\text{m}^3$ )		Accuracy (%)	
$PM_{2.5}$	$PM_{10}$	$PM_{2.5}$	$PM_{10}$
38	398	19	8
46	510	19	7
77	632	17	8
88	726	19	8
136	1016	20	9

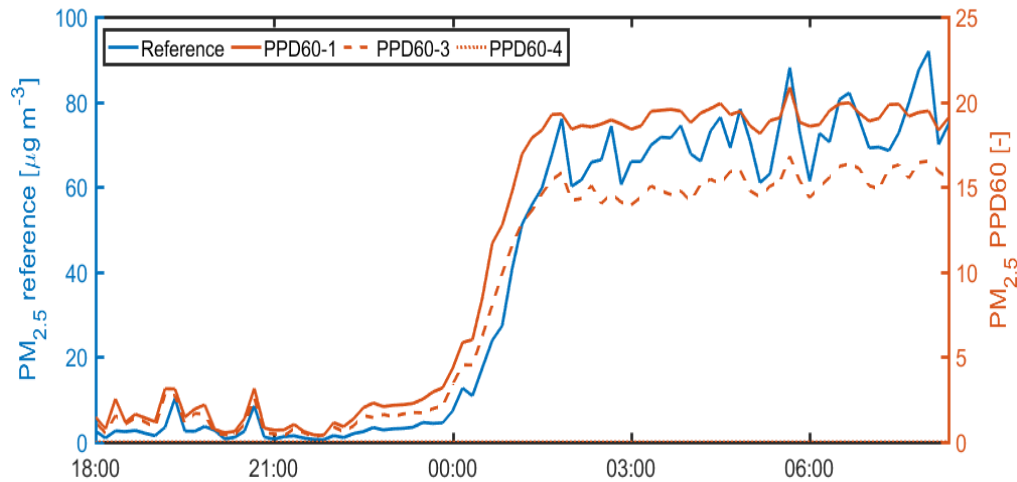
**Data recovery**  
 100% for two units  
 46% for one unit

**Influence of T and RH**  
 One unit was susceptible to changes in RH





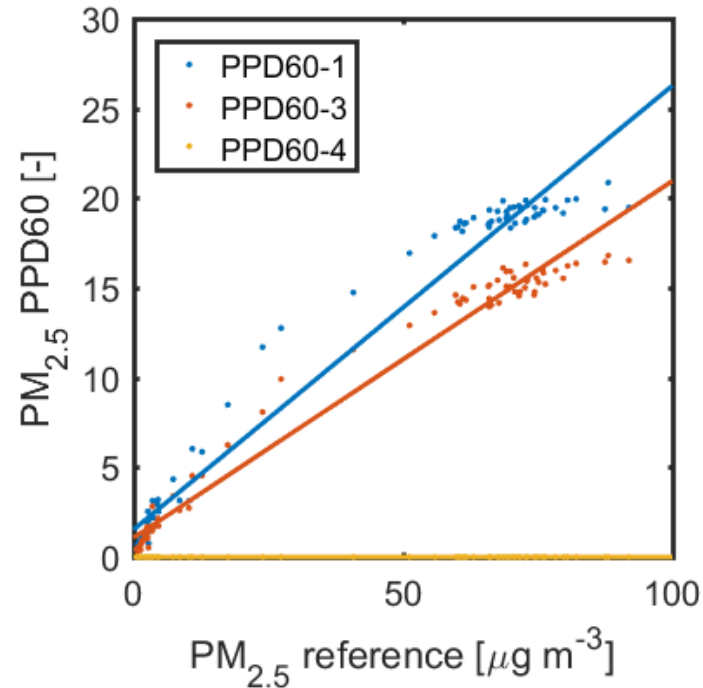
## Uncalibrated sensor vs reference



Accuracy (uncalibrated)

Reference mean ( $\mu\text{g}/\text{m}^3$ )	Accuracy (%)
PM <sub>2.5</sub>	PM <sub>2.5</sub>
38	28
46	2
77	22
88	20
136	15

## Linearity before calibration



$R^2 \geq 0.96$

- slopes are around 0.71 for PM<sub>2.5</sub>

### Data recovery

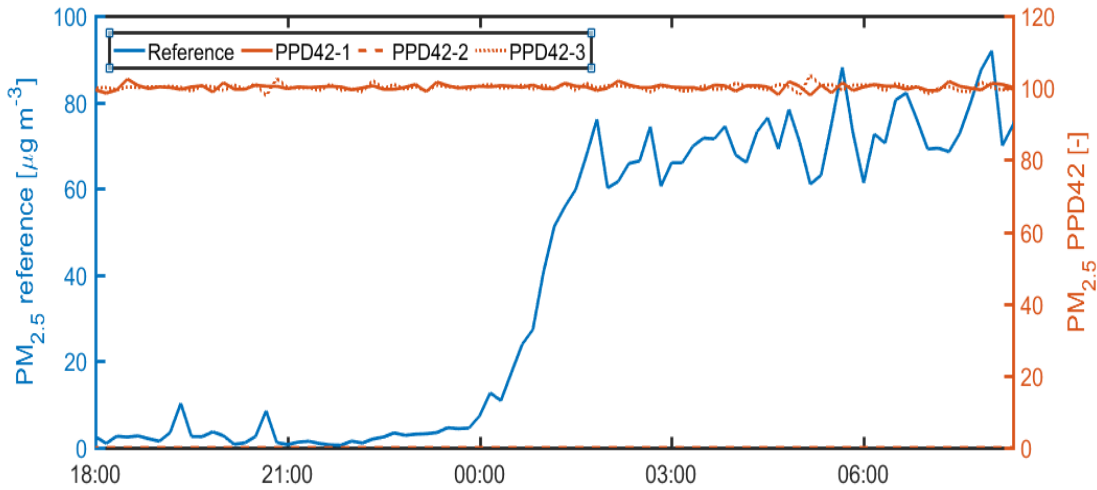
- 97% unit 1
- 81% unit 3
- 0% unit 4

### Influence of T and RH

Changes in RH **slightly affect** the sensor.  
 Changes in T do **not affect** the sensor.



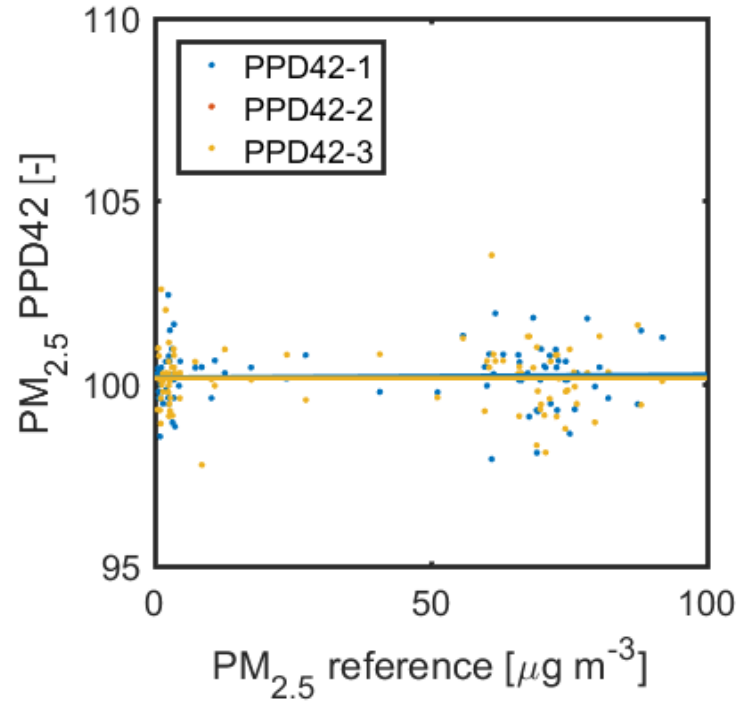
## Uncalibrated sensor vs reference



Accuracy (uncalibrated)

Reference mean ( $\mu\text{g}/\text{m}^3$ )	Accuracy (%)
PM <sub>2.5</sub>	PM <sub>2.5</sub>
38	-58
46	-18
77	70
88	86
136	74

## Linearity before calibration



$R^2 < 0.01$

- slopes due to lack of linearity not determinable

### Data recovery

- 97% unit 1
- 0% unit 2
- 100% unit 3

### Influence of T and RH

Changes in RH **slightly affect** the sensor.

Changes in T do **not affect** the sensor.